



The Research Project Canvas

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Research Project Canvas Project title: **VISION-2** Designed by: **MARTINS** Date: **FEB. 14**

Problem What real world problem are we solving? Why should the problem be solved? What is the specific knowledge gap? self-driving cars threaten cyclists Can't read facial expressions can't interpret body language Cars can't communicate	Objectives What main objective will move us toward solving the identified problem? What are the specific sub-objectives of the project? Read cyclist's body language Adapt self-driving car movement Communicate with cyclists	
Results and Impact What new knowledge will be generated? How will the project impact the world? Who benefits and in what way? Typical results: New methods Development procedures Code Models New knowledge Possible impacts: Competitive advantage Environmental or social benefits Increased awareness Change in values, beliefs, attitudes Better education Economic gains Policy change Cyclist body language recognition Open source ML code for self-driving cars Impact: 70% fewer cyclist injuries Pictograms for display	Participants Which key participants will allow us to reach the objective? What are the strengths of each participant? Which is each partner going to do? How will partners complement each other? Key accomplishments: Recent publications Previous teamwork Consistent strength Role of each participant Noteworthy related results: Jane = body language Me = neural network Robert = pictograms	Methodology What methodology will allow us to reach our objective? What experiments do we need to perform and what do we expect? How should we divide the work into smaller units (workflows)? How are the different units related? What is the output? Methodology flow: Population Sample size Employment method Data Model Validation Deep convolutional Neural Network Pictogram questionnaire NEURAL NETWORK GESTURES BODY LANGUAGE RESPONSE COMMUNICATION VIDEOS
Dissemination Who is the target audience? How do we reach them? Who and how will explain the results? What knowledge can be shared? What IP has to be protected? Typical dissemination means: Scientific journals Conference presentations Public repositories The internet Workshops/meetings/webinars Appointments Podcasts Training Treatment mode Training for industry Press releases for gen. public Five top-level papers	Timeline How long will the project take? When are specific activities planned to occur? When will we reach important milestones? Who contributes what and when? When does Event take place? Typical items of a Gantt Chart: Work packages Tasks Milestones Deliverables Interdependencies Dependencies Y1 Y2 Y3 BODY LANGUAGE D1 GESTURES D2 RESPONSE D3 COMMUNICATION D4	Resources What key resources does the methodology require? How do we access the required resources? Types of resources: Physical equipment Prior know-how Key partners Materials Data Patents Co-funding Pool of cyclists for questionnaire Partner-car company Videos from self-driving cars DATA PROTECTION!!!
Funder's requirements What requirements are set by the funding body? Expected budget? Which costs can be funded? Key criteria for project evaluation? Industry partner <500k USD	Budget What are the major cost items? How much will they cost? What is the budget of? 100k = researchers 60k = servers and gear 60k = outsourcing materials publishing 50% Jane, 36% Martins, 20% Rob	

Typical requirements Research aims Budget Eligible costs Security of researchers Type of legal entity Description of output TRK

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By Martins Zaumanis

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Project outline

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Problem Definition

Self-driving cars have revolutionized transportation but face critical challenges in accurately interpreting and reacting to the nuanced behaviors of cyclists. The inability of autonomous vehicles to read cyclists' body language, adapt their movement accordingly, and effectively communicate poses significant safety risks. This gap in vehicular communication and understanding necessitates a solution to prevent accidents and enhance road safety.

Objectives

The VISION-2 project seeks to:

1. Develop a robust system for autonomous vehicles to interpret cyclists' body language accurately.
2. Enhance self-driving car algorithms to adapt movements in real-time in response to cyclists' actions.
3. Establish a two-way communication protocol between self-driving cars and cyclists to ensure clear and proactive interactions.

Methodology

We will employ a multi-faceted approach:

- Utilize deep convolutional neural networks to analyze video feeds and identify key postures and gestures of cyclists.
- Integrate this analysis with the vehicle's decision-making processes to adapt movements and predict cyclist behavior.
- Design pictogram-based communication systems to signal intentions between vehicles and cyclists.
- Conduct extensive testing through simulations and real-world scenarios to refine algorithms and communication protocols.

Resources

Key resources include:

- A pool of cyclists for data collection and questionnaire feedback.
- Advanced computational infrastructure for neural network training and data processing.
- Collaboration with a partnering car company for field tests and integration.

Participants

The project will be undertaken by a diverse team:

- A neural network specialist (referred to as "Me") to lead the development of machine learning algorithms.
- Jane, an expert in body language, will oversee the interpretation of cyclist behavior.
- Robert, specializing in pictograms, will design the visual communication system.

Results and Impact

The VISION-2 project is anticipated to yield:

- A comprehensive system for interpreting cyclist behavior.
- A demonstrable reduction in potential accident scenarios involving cyclists, aiming for a 70% decrease in cyclist injuries.
- A scalable model for vehicular communication that can be adapted beyond cyclists to other vulnerable road users.

Dissemination

We will disseminate findings through:

- Five to seven top-tier journal publications.
- Training modules for industry stakeholders.
- Press releases and general public engagement.
- Participation in relevant industry and academic conferences.

Timeline

The project will span three years, segmented into quarters, focusing on:

- Year 1: Development of neural network models and initial testing (Q1-Q4).
- Year 2: Refinement of models and beginning of field tests (Q1-Q4).
- Year 3: Final testing, refinement, and dissemination activities (Q1-Q4).

Budget

The financial plan includes:

- Research personnel: \$100k.
- Computational resources: \$60k.
- Material and publishing: \$60k.
- The budget allocation between participants is 50% to Jane, 30% to "Me," and 20% to Robert.

Full Proposal Draft

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Problem Definition

Real-World Challenge: Ensuring Cyclist Safety in the Age of Autonomous Vehicles

The advent of autonomous vehicles (AVs) presents a landmark advancement in transportation technology, offering the promise of improved traffic efficiency, reduced congestion, and lowered emission levels. However, the integration of AVs into our transportation ecosystem has surfaced a significant challenge: ensuring the safety of vulnerable road users, particularly cyclists. Cyclists' safety is jeopardized by the current limitations of AVs, which include:

- **Inadequate Perception:** AVs lack the capability to fully interpret the nuanced and dynamic body language of cyclists, which is crucial for predicting their actions and intentions.
- **Insufficient Adaptability:** The existing algorithms governing AVs' movements are not sophisticated enough to dynamically adapt to the unpredictable movements of cyclists, increasing the risk of collisions.
- **Communication Barriers:** There is no established method for AVs to communicate their awareness and intended actions to cyclists, leading to uncertainty and hazardous interactions.

Specific Knowledge Gap

The specific knowledge gap we aim to fill is the development of a comprehensive system that enables AVs to:

1. **Understand Cyclist Body Language:** We need to create an AI-powered framework that can accurately interpret a cyclist's body language in real-time, predicting potential maneuvers and intentions.
2. **Adaptive Movement Algorithms:** We must enhance AVs' decision-making algorithms to dynamically adjust their movements in response to the predicted actions of cyclists.
3. **Bidirectional Communication Protocols:** It is critical to establish a protocol that allows AVs to communicate their awareness and actions to cyclists, creating a safer and more predictable road environment.

The VISION-2 project will address these challenges by leveraging advanced AI techniques, comprehensive data collection, and innovative communication strategies to improve the interaction between AVs and cyclists, thereby reducing accidents and enhancing road safety.

Objectives

Synergistic Goals for Safer Coexistence of Cyclists and Autonomous Vehicles

The VISION-2 project is dedicated to pioneering a triad of objectives to bridge the gap between autonomous vehicular technology and cyclist safety. These objectives are designed to function in concert, each playing a pivotal role in achieving the overarching mission of enhancing road safety.

Primary Aims

- Interpret Cyclist Body Language:** The project's first aim is to develop an advanced AI-based interpretation system capable of deciphering the subtleties of cyclist gestures and positions. This system will use deep learning techniques to analyze visual data, recognize patterns, and predict possible future actions of cyclists on the road.
- Adapt Autonomous Vehicle Movement:** The second aim is to integrate the insights gained from the AI interpretation system into the operational algorithms of autonomous vehicles. This will enable AVs to adjust their trajectories, speed, and signaling in real-time, ensuring more harmonious and safe interactions with cyclists.
- Establish Communication Protocols:** The third aim focuses on the creation of a set of universally comprehensible pictograms and signals that AVs can use to communicate intentions to cyclists. This visual language will be designed to be intuitive, reducing the likelihood of misunderstandings and promoting a safer shared road space.

Sub-Objectives

To support the attainment of these primary aims, the VISION-2 project will pursue several specific sub-objectives:

- Data Collection and Analysis:** Amass a large dataset of cyclist behavior through video recordings and direct observation to train the AI interpretation system with a wide array of scenarios.
- Algorithm Development and Testing:** Develop and iteratively test the AI algorithms that will allow AVs to interpret cyclist behavior, ensuring accuracy and reliability in diverse conditions.
- Pictogram Development:** Design a comprehensive set of pictograms that convey clear messages from AVs to cyclists, leveraging expertise from semiotics and user experience design.
- Stakeholder Engagement:** Conduct workshops and seminars with cyclists, traffic authorities, and AV manufacturers to refine the communication protocols and ensure they meet the needs of all road users.
- Policy Recommendations:** Formulate guidelines and policy recommendations based on the project's findings to inform future regulations on AV and cyclist interactions.

The successful fulfillment of these objectives and sub-objectives will constitute a substantial leap forward in the domain of autonomous vehicle technology, specifically in its capacity to coexist safely with cyclists. The VISION-2 project is committed to a future where roads are shared equitably and safely by all users, powered by the synergy of human ingenuity and artificial intelligence.

Methodology

Innovative and Interdisciplinary Approaches to Enhance Cyclist Safety

The VISION-2 project will employ a comprehensive methodology that encompasses the development of AI technologies, the creation of communication protocols, and the rigorous testing of these systems in simulated and real-world environments.

AI Development for Body Language Interpretation

- **Data Collection:** We will gather a diverse range of video data featuring cyclists in various environments, weather conditions, and traffic scenarios to ensure our neural network is trained on a comprehensive dataset that reflects real-world complexity.
- **Deep Convolutional Neural Network (DCNN):** A DCNN will be designed to process the collected video data, learn from the cyclists' posture and movement patterns, and accurately predict their immediate actions. This network will be trained, validated, and tested using state-of-the-art machine learning techniques.
- **Algorithm Integration:** The predictive model developed by the DCNN will be integrated into the decision-making system of autonomous vehicles. This will involve collaboration with our industry partners to embed and fine-tune the algorithm within the existing vehicle control systems.

Development of Communication Protocols

- **Pictogram Design:** In parallel to AI development, we will initiate the design of an intuitive pictogram-based communication system. This will involve iterative design phases, user testing with both cyclists and drivers, and refinements based on feedback.
- **Questionnaire for Feedback:** A series of pictogram questionnaires will be disseminated to a broad audience, including the pool of cyclists and industry experts, to gather insights on the effectiveness and clarity of the proposed communication symbols.

Testing and Validation

- **Simulation Testing:** Before on-road testing, the integrated systems will undergo extensive simulation testing to ensure safety and reliability. Scenarios will be modeled after the collected data, testing the AI's predictive accuracy and the clarity of the communication protocols.
- **Real-world Testing:** With positive simulation results, we will move to controlled real-world testing in collaboration with our car company partner. This will involve closed-course testing with professional cyclists and drivers to validate the systems' efficacy in real traffic conditions.

Work Packages and Tasks

The methodology will be divided into smaller units of work packages and tasks:

- **Work Package 1:** Data collection and preprocessing.
- **Work Package 2:** Development and training of the DCNN.
- **Work Package 3:** Development of pictogram-based communication protocols.
- **Work Package 4:** Integration of AI predictions with vehicle control systems.
- **Work Package 5:** Simulation and real-world testing.

- **Work Package 6:** Dissemination and stakeholder engagement.

Resources

Strategic Allocation of Assets and Collaborations for Project Success

The execution of the VISION-2 project's ambitious methodology is contingent on the availability and optimal utilization of key resources. We have identified the following critical resources necessary to support our project's lifecycle:

Computational Infrastructure

- **Advanced Computing Power:** To support the intensive computational demands of training deep convolutional neural networks, we require high-performance servers equipped with state-of-the-art GPUs. This will facilitate rapid processing of large datasets and efficient algorithm training.
- **Data Storage Solutions:** Robust data storage systems are essential for managing the extensive video datasets collected during the research phase. We will employ secure, scalable storage solutions to ensure data integrity and accessibility.

Human Resources

- **Expert Personnel:** Recruiting individuals with specialized knowledge in machine learning, data science, and visual communication will be pivotal. Their expertise will drive the development of the AI system and the design of the communication protocol.
- **Cyclist Participation:** A diverse group of cyclists will be engaged to contribute to data collection and feedback on the pictogram questionnaire. This community involvement is crucial for ensuring that the project outcomes are grounded in user experience.

Material Resources

- **Data Collection Equipment:** High-resolution cameras and sensors will be deployed to capture cyclist behavior in high fidelity, ensuring quality data input for algorithm training.
- **Prototyping Materials:** For the development and testing of the pictogram communication system, we will require materials for creating physical and digital prototypes.

Collaborative Partnerships

- **Industry Partner:** Our partnership with a leading car company is vital for integrating and testing the developed systems in actual vehicle prototypes. Their contribution extends beyond material resources to include invaluable industry insights and expertise.
- **Academic and Research Alliances:** Collaborations with academic institutions will enhance our research capabilities and provide access to additional expertise, peer review, and validation mechanisms.

Financial Resources

- **Project Funding:** Secured funding of under \$500k from a combination of industry partnerships and research grants will cover the expenses related to personnel, equipment, materials, and dissemination activities.

Access to Resources

- **Data Protection and Ethical Considerations:** All resource utilization will adhere to strict data protection regulations and ethical standards. Participants' privacy will be safeguarded, and all data usage will be compliant with relevant legal frameworks.

Participants

Harnessing Expertise for Collaborative Innovation

The VISION-2 project brings together a multidisciplinary team, each member selected for their unique contributions to the project's success. The participants and their roles are as follows:

Core Team Members

- **AI Specialist ("Me"):** As the neural network expert, I will lead the development and implementation of the deep learning algorithms crucial for interpreting cyclist behavior. My expertise in machine learning and data analysis will be pivotal in creating a predictive model that is both accurate and reliable.
- **Body Language Expert (Jane):** Jane brings to the project a wealth of knowledge in human behavior and nonverbal communication. Her insights will be invaluable in developing the criteria for the AI model to interpret cyclist gestures and in validating the pictogram designs for efficacy and user-friendliness.
- **Pictogram Designer (Robert):** Robert's role encompasses the creation of the visual communication system. His background in graphic design and semiotics will ensure that the pictograms are not only intuitive but also culturally and universally comprehensible.

Supporting Participants

- **Cyclist Volunteers:** A diverse group of cyclists will be engaged to provide video data and feedback on communication protocols. Their real-world experience and participation in questionnaires will enrich the project's data pool and help refine the pictogram system.
- **Industry Partners:** Collaboration with an automotive company will lend practical insight into the integration of our system with current vehicle technologies. They will also provide resources for prototype testing and potential implementation in future product lines.

Complementary Skills

Each participant's expertise is carefully aligned with the project's needs:

- **"Me"**: I will focus on algorithm development, overseeing the data analysis, and ensuring the technical robustness of the AI system.
- **Jane**: Her role will be crucial in interpreting the data to ensure that the AI system accurately reflects real-world cyclist behavior. She will also contribute to the development of the training modules for industry stakeholders.
- **Robert**: Beyond designing the pictograms, Robert will manage the dissemination of visual materials and assist in the creation of public engagement strategies.

Collaborative Dynamics

The collaboration between participants will be structured to maximize the synergy of their combined expertise:

- **Interdisciplinary Workshops**: Regular workshops will be conducted to facilitate knowledge exchange and ensure that the AI algorithms and communication protocols are developed with a holistic understanding of the project's objectives.
- **Joint Testing Sessions**: Field tests will involve all participants, providing opportunities for real-time feedback and iterative improvements to the system.

Contribution Timeline

Each participant's involvement will be mapped across the project's timeline, with specific roles in data collection, system development, testing, and dissemination phases, ensuring a cohesive and coordinated effort towards achieving the project's aims.

Results and Impact

Project VISION-2: Pioneering Safer Roads for Cyclists and Autonomous Vehicles

The VISION-2 project endeavors to create groundbreaking results that will significantly impact autonomous driving technologies and cyclist safety. The expected outcomes are twofold: direct advancements in technology and the broader societal impact of these advancements.

Technological Advancements

- **AI-Powered Cyclist Behavior Interpretation System**: A sophisticated model capable of interpreting a cyclist's body language in real time with high accuracy, allowing for predictive behavior analysis.
- **Adaptive Movement Algorithms for Autonomous Vehicles**: Enhanced algorithms that enable vehicles to adjust their movements dynamically in response to cyclist actions, fostering safer interactions.
- **Visual Communication Protocol**: A set of pictograms that represents a new, intuitive language for interaction between autonomous vehicles and human road users.

Societal and Safety Impact

- **Increased Safety on Roads:** The deployment of this technology aims to result in a 70% reduction in cyclist injuries, a significant improvement in road safety for vulnerable users.
- **Scalable Safety Solutions:** The methodologies and technologies developed can be adapted to other areas of autonomous vehicle interaction, potentially reducing accidents with pedestrians and other non-motorized road users.
- **Informed Policy Making:** The research findings will provide empirical data to inform policy recommendations for urban planning and autonomous vehicle regulations.

Economic and Environmental Benefits

- **Reduced Healthcare Costs:** Fewer injuries translate to lower healthcare costs and economic burdens on families and communities.
- **Sustainable Urban Environments:** Safer interactions between cyclists and vehicles promote cycling as a viable and safe mode of transportation, contributing to greener cities.

New Knowledge and Educational Contributions

- **Scientific Publications:** Dissemination of research findings through scientific papers will contribute to the body of knowledge in AI, autonomous vehicles, and road safety.
- **Training Modules:** Development of educational materials for industry stakeholders, fostering a deeper understanding of autonomous systems and cyclist safety.

Dissemination

Strategically Communicating VISION-2's Breakthroughs

The dissemination strategy for VISION-2 is designed to ensure that the results of the project reach all pertinent stakeholders, from industry experts to the general public, maximizing the project's impact.

Target Audiences and Channels

- **Academic Community:** We will publish our findings in five to seven top-level peer-reviewed journals in fields relevant to autonomous driving, AI, and traffic safety. By presenting at leading international conferences, we will engage with fellow researchers and industry professionals.
- **Industry Stakeholders:** Training modules and workshops tailored for automotive manufacturers and technology companies will be developed to facilitate the implementation of our results in next-generation autonomous vehicles.
- **General Public and Policy Makers:** Press releases and accessible summaries of our work will be distributed to ensure public awareness and to inform policy makers who can drive legislative changes based on our findings.

Knowledge Sharing and Intellectual Property

- **Open Source Code for AI Systems:** In line with fostering a collaborative and progressive scientific environment, the AI system's code will be made available to the research community under an open-source license, encouraging further innovation and development.
- **Pictograms for Public Display:** The developed communication protocols, including the pictogram system, will be shared with public entities and included in driver education programs to familiarize the public with the new communication methods.

IP Protection and Ethical Considerations

- **Intellectual Property:** While fostering open innovation, we will protect the proprietary aspects of our technology through patents, ensuring that commercial benefits are aligned with the project partners' interests.
- **Ethical Standards:** All dissemination activities will adhere to the highest ethical standards, ensuring that data privacy and individual rights are respected.

Monitoring and Evaluation

- **Feedback Mechanisms:** We will establish feedback channels to gauge the effectiveness of our dissemination efforts, using surveys and engagement metrics to refine our approach continually.
- **Impact Assessment:** The long-term impact of the project on both the scientific community and the general public will be assessed, ensuring that the project's benefits are realized and communicated effectively.

Timeline

Strategic Phasing for Project Milestones and Deliverables

The VISION-2 project will be conducted over a span of three years, divided into quarterly phases, each with specific goals and deliverables. The project timeline integrates development, testing, and dissemination activities, ensuring a logical progression and timely completion of the project goals.

Year 1: Foundation and Development

- **Q1:**
 - Project kickoff and team alignment.
 - Commencement of data collection from cyclist volunteers.
 - Initial development of the deep convolutional neural network (DCNN).
- **Q2:**
 - Continuation of data collection with an expanded variety of scenarios.
 - Iterative training and refining of the DCNN.
- **Q3:**
 - Preliminary testing of the DCNN's predictive capabilities in simulated environments.
 - Development of the first set of pictograms for communication.

- **Q4:**
 - Assessment of the DCNN's performance and adjustments based on Q3 results.
 - Pictogram refinement and user feedback collection.

Year 2: Integration and Initial Testing

- **Q1:**
 - Integration of the DCNN with autonomous vehicle control systems.
 - Development of the pictogram questionnaire for broader public input.
- **Q2:**
 - Simulation testing of the integrated system, focusing on the interaction between the AI and vehicle control systems.
 - Analysis of pictogram questionnaire results and further refinement.
- **Q3:**
 - First round of controlled real-world testing with the industry partner.
 - Adjustment of communication protocols based on real-world testing feedback.
- **Q4:**
 - Extended real-world testing with a diverse group of cyclists and environmental conditions.
 - Development of training modules for industry stakeholders.

Year 3: Finalization and Dissemination

- **Q1:**
 - Final refinement of AI algorithms and vehicle integration.
 - Finalization of the pictogram communication system.
- **Q2:**
 - Preparation of findings for publication in academic journals.
 - Launch of training modules for industry stakeholders.
- **Q3:**
 - Submission of research papers to journals and conferences.
 - Public engagement activities and press releases.
- **Q4:**
 - Final project review and evaluation of dissemination impact.
 - Final reporting to funders and stakeholders.
 - Planning for future research directions based on project findings.

Budget

Fiscal Planning for VISION-2: Optimizing Resource Allocation

The VISION-2 project is projected to operate within a budget of less than \$500,000 USD, strategically allocated across various categories to ensure the effective execution of all project components. Below is the proposed financial plan, which provides a detailed budget breakdown for the project's three-year duration.

Personnel Costs

- **Research Personnel:** \$100,000
 - Allocation for salaries of the core research team, including the AI specialist, body language expert, and pictogram designer.
 - Compensation for support staff and technical assistants involved in data collection and analysis.

Computational Resources

- **Servers and High-Performance Computing Gear:** \$60,000
 - Acquisition of high-performance servers with advanced GPUs for AI model training and data processing.
 - Provision for ongoing maintenance and upgrades to computational infrastructure.

Materials and Publishing

- **Data Collection Equipment:** \$30,000
 - Purchase of high-resolution cameras and necessary sensors for capturing cyclist behavior.
- **Publishing and Dissemination Costs:** \$30,000
 - Costs associated with open-access publishing fees for journal articles.
 - Production of dissemination materials, including training modules and pictogram sets.

Travel and Miscellaneous Expenses

- **Travel for Conferences and Meetings:** \$10,000
 - Provision for travel expenses related to conferences, workshops, and stakeholder meetings.
- **Contingency Fund:** \$10,000
 - Reserved funds to address unforeseen expenses or adjustments in project scope.

Direct Project Costs

- **Research and Development:** \$260,000
 - Direct costs associated with research activities, including development, testing, and validation of the AI system and communication protocols.
- **Industry Collaboration and Testing:** \$100,000
 - Expenses related to collaboration with the industry partner for real-world testing and integration.

Indirect Costs

- **Administrative and Overhead:** \$40,000
 - Indirect costs covering administrative support, utilities, and institutional overheads.

Budget Allocation Among Partners

- **Jane (Body Language Expert):** 50% of the budget for her significant role in research and development.
- **"Me" (AI Specialist):** 30% for leading the technical development and integration of the AI system.
- **Robert (Pictogram Designer):** 20% for designing the communication system and overseeing its implementation.

Abstract

Enhancing Cyclist Safety in Autonomous Driving: The VISION-2 Project

As autonomous vehicles (AVs) become more prevalent, the safety of vulnerable road users, especially cyclists, has emerged as a critical concern. The VISION-2 project addresses this challenge by developing an AI-based system that enables AVs to interpret cyclists' body language accurately, adapt their movements dynamically, and communicate their intentions clearly. This comprehensive approach promises to significantly reduce the incidence of accidents and injuries among cyclists.

The project is underpinned by a robust methodology involving the development of deep convolutional neural networks (DCNN) trained on extensive datasets of cyclist behavior. This AI system will be integrated into AVs' decision-making processes, enhancing their ability to predict and respond to cyclists' actions on the road. Complementing this, a set of intuitive pictograms will be designed to facilitate clear communication between AVs and cyclists.

A multidisciplinary team of experts leads the project, leveraging their diverse skills to address the complex challenges of AV-cyclist interactions. The project is structured into six work packages, encompassing data collection, AI development, pictogram design, system integration, testing, and dissemination.

With a budget of under \$500,000 and a timeline of three years, the VISION-2 project is financially and temporally feasible. The anticipated results include a 70% reduction in cyclist injuries, substantial contributions to the scientific literature, and the creation of educational resources for industry stakeholders.

Dissemination efforts will target academic, industry, and public domains, ensuring that the project's outcomes are shared widely and effectively. Open source AI tools and educational materials will be made available to the research community, while the protection of intellectual property will secure the commercial interests of project partners.

The VISION-2 project represents a significant step forward in ensuring the harmonious coexistence of AVs and cyclists, contributing to safer, more sustainable urban environments.

Logos

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